

TITLE

"Method and apparatus for joining the edges of a tubular knitted article"

SPECIFICATION

5 The present invention refers to a method and apparatus for joining the edges of a tubular knitted article, such as a stocking, upon the completion of the latter on a circular machine.

Methods and machines are known for closing tubular articles.

10 In particular, the European Patents EP-0.592.376 and EP-0.635.593 disclose how to close tubular articles, specifically with a hooked-up finish, by carrying out the above said operation on the outer or right-side out of the article. The document Ep-0.942.086 discloses how to hook-up
15 the fabric edges on the desired side by applying an operating method which takes into account the type of article's manufacturing machine. In particular, provision is made for possibly hooking-up on the inner or inside-out side of the article by removing in advance the same article from a one-
20 cylinder machine.

The above mentioned solutions, although representing undoubtedly an advance with respect to the existing systems, suffer from some drawbacks. One drawback relates to the excessive handling of the stitches, that is, an excessive
25 number of transfers thereof to and from various members which brings about a higher possibility of losses and/or damages of the same stitches. Another drawback is the fact that the means and machines so constructed may result relatively complex and thus apt to be industrialized only by industries
30 exhibiting advanced technology and a high level of know-how. The above drawbacks, which relate to one-cylinder machines, hold true also in the case of removing the articles from the lower cylinder of a two-cylinder machine, that is, in case the stitches are removed with their right side out.
35 The object of the present invention is to overcome the said

drawbacks.

This result has been achieved, according to the invention, by providing a method and apparatus having the features disclosed in the independent claims. Further characteristics 5 being set forth in the dependent claims.

Among the advantages of the present invention, one is that it provides the solution for the major problem concerning the case in which the article is removed from the cylinder of a one-cylinder machine or the lower cylinder of a two-cylinder 10 machine, with its right-side out and by a limited number of stitch transfers; in fact, one important characteristic of the operating method according to the present invention is that the transfer of the stitches from the first semi-rank takes place by a 180°-overturning of the same means which 15 have carried out the removal thereof and, thus, without any transfer of the stitches onto further means, thereby limiting the handling thereof. Moreover, the apparatus implementing the method according to the invention results extremely simple to make and reliable even after a prolonged service 20 life.

These and other advantages and characteristics of the invention will be best understood by anyone skilled in the art from a reading of the following description in conjunction with the attached drawings given as a practical 25 exemplification of the invention, but not to be considered in a limitative sense, wherein:

- Fig. 1 is a front view, with parts in section, of a head for knitting an article (a stocking, in particular), which shows the head upon completion of the knitting of the 30 stocking in correspondence of the toe which remains open;
- Fig. 2 shows the machine of the preceding figure, upon the subsequent operating phase in which the plate is lifted to make the knitting head of the machine accessible, and in which the needles are lifted so as to move each stitch up to 35 the so-called "unloading" position, that is, below the

respective latch of the needle;

- Fig. 3 refers to the phase in which, according to the invention, a movable carrier provided with removal means is moved onto the knitting head of the machine and the needles are further lifted so as to take the stitches to be removed above the sinkers;

- Fig. 4 refers to a phase in which some of the above removal means - to be referred to later on also as punches - are moved close to the relevant heads of the needles;

10 - Fig. 5 refers to a phase in which stitch-pushing means, which can be used during the removal phase and are hereinafter referred to also as hooks - are moved below the stitches to be removed and disposed in a closing configuration;

15 - Fig. 6 refers to a phase for lifting the hooks and, along with them, the stitches which disengage from the needles and pass onto the removal means;

- Fig. 7 shows the lifting of the punches which move away from the needles, and the consequent lifting of the article 20 now released from the knitting head of the machine;

- Fig. 8 shows the phase in which the carrier is moved away, along with the article supported thereon, from the knitting head of the machine;

25 - Fig. 9 shows a subsequent phase in which the article is moved to a hooking-up station and inserted within a inside-out-turning tube presented by the same station;

- Fig. 10 shows the phase in which the inside-out-turning tube is lifted, thereby allowing the article to turned inside-out achieving the turning inside-out of the article 30 with the initial end thereof oriented upwards above the rank of stitches removed from the punches;

- Fig. 11 shows the final stage of the lifting operation, in which the turning-inside-out tube remains engaged with relevant supporting means (not shown) in correspondence of 35 its upper end, while the lower end of the tube remains free

and above the plane of the removed stitches, with the article resulting fitted on the outer side of said tube;

- Fig. 12 shows the phase in which the stitches of a first semi-rank are overturned through substantially 180° about the 5 diametral axis which ideally divides the circumference of the removed rank into two semi-ranks;

- Fig. 13 shows the phase in which, after the overturning shown in the preceding figure, each member for the removal of the first semi-rank is in correspondence of a member for the 10 removal of the second semi-rank, with the respective free ends thereof being close to each other;

- Fig. 14 shows the phase in which the first rank-removing members are brought back to their starting position by operating the above said overturning in the opposite 15 direction;

- Fig. 15 shows the stitch-supporting means - so-called spines - which are moved close to the punches during the hook-up phase;

- Fig. 16 shows how the stitches are transferred with a 20 longitudinal push by suitable means, in the example a crown coaxial to the circumference defined by the punches;

- Fig. 17 refers to the phase of hooking-up the stitches and/or pairs of stitches, fitted on the spines by hook-up means, by making the necessary chain-closing knots;

- Fig. 18 refers to the phase in which the hooked-up stitches 25 are released from the spines;

- Fig. 19 shows an enlarged perspective view of a hook;

- Fig. 20 is a side view of a possible embodiment of a 30 movable carrier according to the present invention;

- Fig. 21 is a view in section taken on line B-B of the movable carrier shown in Fig. 20;

- Figs. 22, 23 and 24 are, respectively, a bottom view, an axonometric view, and a sectional axonometric view of the 35 movable carrier shown in the preceding figures;

- Fig. 25 is a side view of a movable carrier during the

overturning of a relevant sector of means for the removal of the first semi-rank;

- Fig. 26 is a view in section taken on line F-F in Fig. 25;

- Fig. 27 is a front view of the movable carrier, that is, a 5 view angularly shifted through 90° with respect to Fig. 25;

- Fig. 28 is a view in section taken on line E-E in Fig. 27;

- Figs. 29, 30 and 31 show the movable carrier during the overturning phase, in a first axonometric bottom view (Fig. 29) from a point of view similar to that of Fig. 25, a second 10 axonometric bottom view (Fig. 30) from a point of view similar to that of Fig. 27, and a sectional axonometric view (Fig. 31);

- Fig. 32 is an exploded side view of the movable carrier shown in the preceding figures;

15 - Fig. 33 is a sectional view taken on line D-D in Fig. 32;

- Figs. 34 and 35 show axonometric bottom views of the carrier, from points of view similar respectively to those of Figs. 32 and 33;

- Fig. 36 is a front view of an embodiment, according to the 20 invention, of an inside-out-turning device with coaxial tubes in open condition;

- Figs. 37, 38 and 39 show the inside-out-turning device of Fig. 36 respectively in a sectional view taken on line A-A in Fig. 36, a sectional view taken on line B-B in Fig. 36, and an 25 axonometric view;

- Fig. 40 is an axonometric view similar to that of Fig. 39, with the inside-out-turning device being sectioned longitudinally;

- Figs. 41 and 42 refer, respectively, to a further 30 axonometric view of the device of Fig. 36 and to an enlarged detail thereof;

- Fig. 43 is a front view of one embodiment of the inside-out-turning device of Fig. 36 shown in closed condition;

- Figs. 44, 45 and 46 show the inside-out-turning device of 35 Fig. 43 respectively in a sectional view taken on line C-C in

Fig. 43, a sectional view taken on line D-D in Fig. 43 and in axonometric view;

- Fig. 47 is an axonometric view similar to that of Fig. 46, with the inside-out-turning device being sectioned 5 longitudinally;

- Figs. 48 and 49 refer, respectively, to a further axonometric view of the device in closed condition as in Fig. 43, and to an enlarged detail thereof;

- Figs. 50 and 51 are axonometric views of, respectively, the 10 outer tube only, and the inner tube only, both tubes making part of the exemplary inside-out-turning device shown in the preceding figures;

- Figs. 52 and 53 refer to enlarged details, respectively, of Fig. 50 and Fig. 51;

15 - Fig. 54 is a rear view of a removal member making part of a pivoting semi-rank;

- Fig. 55 is a sectional view of the removal member taken on line A-A in Fig. 54;

20 - Fig. 56 is axonometric view of the removal member sectioned as in Fig. 55;

- Figs. 57, 58 and 60 show, respectively, the member of Fig. 54 in axonometric view, in side view, and in top (Fig. 59) and bottom (Fig. 60) axonometric views;

- Fig. 61 is a rear view of a removal member making part of a 25 fixed semi-rank;

- Fig. 62 is a sectional view of the removal member taken on line B-B in Fig. 61;

- Fig. 63 is an axonometric view of the removal member sectioned as in Fig. 62;

30 - Figs. 64, 65, 66 and 67 show respectively the member of Fig. 61 in axonometric view (Fig. 64), side view (Fig. 65), and in top (Fig. 66) and bottom (Fig. 67) axonometric views;

- Fig. 68 is a side view of the engagement of a needle with a removal member in a removal phase;

35 - Figs. 69 and 70 are axonometric views, respectively, of the

engagement of Fig. 68 and of a detail thereof;

- Fig. 71 is a side view of two removal members engaged with each other during the transfer of a stitch;

5 - Figs. 72, 73 and 74 show, respectively, a longitudinal section, an overall axonometric view, and an axonometric view of a detail of the removal members of Fig. 71;

- Figs. 75 and 76 are a side view of a removal member during a removal (Fig. 75) and transfer (Fig. 76) of a stitch;

10 - Figs. 77, 78, 79 and 80 are sectional views of details of the movable carrier during the phases subsequent to said removal, showing the members for moving the pivoting removal members and the stitch-pushing means during said transfer;

15 - Figs. 81, 82, 83 and 84 show sectional details of an alternative embodiment of the movable carrier during the phases subsequent to said removal;

- Fig. 85 is an outline side view of the movable carrier positioned on the machine's knitting head with a support column and an actuator for the vertical movement thereof;

20 - Fig. 86 is a plan view of the movable carrier outlined in Fig. 85, with the actuator for the movement thereof from and to the knitting and hook-up stations;

25 - Fig. 87 shows a phase alternative to that shown in Fig. 15, in which a hook-up needle is moved close to the punches which support the stitches onto the movable carrier, in order to hook-up stitches and/or pairs of stitches, fitted onto the punches, by means of the hook-up needle, by making the necessary chain-closing knots directly on the punches;

- Fig. 88 refers to the phase, similar to that of Fig. 18, of releasing the hooked-up stitches.

30 With reference to the figures of the attached drawings, an apparatus according to the invention comprises a movable carrier 300 which is moved close to and away from a knitting head 100, and can be rotated and vertically displaced as well. Figs. 85 and 86 show schematically the movement of carrier 300. In the example, the movable carrier 300 is

supported by a relevant arm 10 horizontally disposed. The arm 10 is keyed on the sleeve 302 which is fitted on a relevant hollow column 301. Provided inside the column 301 is a pneumatic lifting cylinder 303, whose rod 308 is fixed inside 5 the sleeve 302 in correspondence of the proximal end 307 of the arm 10. In this way, an extension of rod 308 corresponds to a lift of the arm 10 and of the movable carrier 300 as well supported by the latter. The lower portion 309 of the sleeve 302 is provided with a toothing 305. Also provided is 10 a pneumatic cylinder 306, horizontally disposed, whose rod 310 supports a rack 304 complementary to the toothing 305 and meshing therewith. The travel of rod 310 drives into rotation the sleeve 302 about its longitudinal axis a-a and, consequently, causes the supported movable carrier 300 to 15 rotate as well. Moreover, the toothing 305 moves to a height Q corresponding to the vertical travel of the sleeve onto the column 301 (or longer than the latter); this allows rotating the arm 10 while displacing it up to different levels. Again with reference to the accompanying drawings, and in 20 particular to Figs. 1-18, the knitting head 100 is provided, in a known manner, with a cylinder 1, needles 2, sinkers 3, and a sinkers case 4. The completion of an article 6, such as a stocking, is made on the knitting head 100 with the use of a plate group 5. Upon completion of the knitting, as 25 illustrated in Fig. 1, the stocking or article 6 has the configuration in which the tubular part is knitted and the toe remains open.

At this point, the plate 5 is lifted (see Fig. 2) in a known manner which, therefore, will not be described herein in 30 detail. At the same time, the needles 2 of the knitting head 100 are lifted so as to move each stitch of article 6 to the position so-called "unloaded" in technical jargon, that is, to a level along the needle which is below the latch 201 of the needle 2 (numeral 200 indicating the needle's head). 35 As mentioned before, and as shown in Fig. 3, the apparatus in

question comprises the movable carrier 300 supported by the arm 10 which allows the vertical and rotational movement thereof. After the plate 5 is moved away, the movable carrier 300, provided with means for the removal of the article, is 5 superimposed to the knitting head 100. In this phase, the needles 2 are further lifted so as to move the stitches above the sinkers 3.

Before describing the operation of the apparatus any further, let us point out the characteristics of the movable carrier 10 300 by making reference in particular to Figs. 19-35. The movable carrier 300 exhibits a support body 11 on which

relevant hooks 14 are fixed and intended to move the stitches during the removal of the needles 2 from the knitting head 100. The supporting body 11 has a hollow cylindrical shape 15 with two cross-sections: one upper cross-section of greater diameter 110 and one lower cross-section of smaller diameter 111.

The hooks 14 are inserted into a corresponding number of slots 130 vertically disposed and presented by a hook-supporting crown 13 located externally and coaxially to the 20 body 11 which supports the movable carrier 300.

Moreover, the support body 11 exhibits, in correspondence of the region connecting the upper 110 with the lower 111 section, a projecting peripheral edge or frame 112. Coming to rest on the frame 112 is a hollow cylindrical element 12 25 which defines a cam. The cam element 12 results interposed between the body 11 and the crown 13 supporting the hooks 14.

As best shown in Fig. 19, the hooks 14 have, when viewed laterally, a substantially "L" shape, with the short leg 145 of the "L" being disposed below. The upper end 140 of the 30 hooks 14 is inserted into an annular cavity 131, of rectangular cross-section, formed on the outside of crown 13.

In correspondence of the said upper end 140, the hooks 14 exhibit a groove 141 on their outer side (that is, on the side facing centrifugally relative to the movable carrier 35 300). On the inner side (that is, centripetally with respect

to carrier 300), the end 140 has a triangular portion defining a step 142 connected with the apex 144 of the upper end 140 via an oblique portion 143, that is, a portion with oblique edge to the longitudinal development of the stem of 5 hook 14.

Housed within the grooves 141 of hooks 14 is an elastic ring (designated by numeral 8 in Fig. 13 only, for the sake of clarity) which retains the said ends 140 inside the cavity 131 of crown 13. In this way, in the absence of further 10 interventions, the oblique portions 143 of the hooks result in contact with and parallel to the vertical wall of cavity 131, as they are kept so retained by the elastic reaction force of the above mentioned ring. This determines an outwardly inclination of the stems of hooks 14, which, owing 15 to the action of the elastic ring, result in an open configuration such as that shown also in Figs. 3 and 4. Besides, the presence of the step or tooth 142 determines a restraint to the downward displacement of the hooks 14 within the slots 130 where they are inserted.

20 Provided externally to the crown 13 is a ring 15 (hereinafter also referred to as "hook-closing ring") intended for moving the hooks 14. The ring 15 is fitted on the crown 13 and is able to slide vertically relative to the same crown. Provided on the hook-closing ring 15 are one or more helicoidal slots 25 150. The helicoidal slots 150 act like cams able to determine the vertical movement of the hook-closing ring 15 in correspondence of the rotational movement of relevant pivots inserted into the slots 150.

Moreover, oblique slots 120 are formed on the cam element 12 30 to receive corresponding pivots 132 (in Fig. 28, numeral 132 designates the axis of one of the pivots 132) which connect the cam element 12 with the crown 13 so as to allow the vertical movement of the latter upon the displacement of pivots 132 within the cams defined by the oblique slots 120.

35 In Fig. 28, besides, numeral 134 designates a hole, and

numeral 135 designates the axis of the pivot inserted therein and able to connect the support body 11 with the crown 15. Provided on the lower portion of the support body 11 are two groups of removal members 26, 25 (also called punches in the 5 present description) to be associated, respectively, with the first and second semi-rank of the article knitted on the knitting machine 100. In some of the attached figures, only one punch or removal member 25 or 26 is shown, for the sake of clarity, when a plurality of these members is provided in 10 repeating series, such as in Figs. 23, 25, 28, 29 and others. Referring now to Figs. 3-18, fixed in the left side of the lower portion of the support body 11 is a crown 20 supporting the removal members 25 of the second semi-rank. As best viewable in Fig. 34, the crown 20 has a half thereof provided 15 with seats for the punches 25. The removal members 26 of the first semi-rank are disposed on a semicrown 21 supported by a semicircular sector 22 hinged to the lower portion 11 of body 11 in correspondence of two diametrically opposite hinges 23. As will be described later on in greater detail, the 20 semicircular sector 22 can be rotated through 180° so as to dispose the semicrown 21 of the first semi-rank below the crown 20 of the second semi-rank. Moreover, with reference in particular to Fig. 30, provision is made for cylindrical containers 88 on the semicircular sector 22 to receive 25 stitch-pushing springs to be described below, while holes 89 are provided for the passage of vertical bars 16 described with reference to Figs. 75-80, and holes 87 for the passage of screws (not shown) for fixing the crown 20 to the body 11. In the illustrated exemplary embodiment (as best illustrated 30 in Figs. 61-67), the removal members 26 of the first semi-rank are essentially made up of a rectilinear and flat body which is tapered in its distal end 251. In correspondence of said end 251, on the side in which the taper begins, a notch 252 is formed within the thickness of the said body to 35 receive the needle 2 of the knitting head 100 during the

removal phase (as illustrated in Figs. 68-70). On the opposite or proximal side, the removal member 26 exhibits a stem 250 by which it is retained firmly by the support means defined by the semicrown 21. The removal members 25 of the 5 second semi-rank (see Figs. 55-60) are like those of the first semi-rank above described, as far as the free end 251 and the cavity 252 allowing the engagement thereof with the needle of the knitting machine are concerned, but they differ in the stem's region. (In Fig. 69, numerals 25 and 26 refer 10 generically to a removal member which is similar for both first and second semi-rank; Fig. 70 also shows a generic stem 250 as this part is similar for the first and second semi-rank). The above characteristic differentiation of the stem's region is due to the difference of the support means (that 15 is, crown 20) which allow an oscillatory movement with radial direction, that is, with "in-out" direction with respect to the circumference of the needles. This results of advantage in allowing a good covering during the engagement for the transfer of the stitches of the first semi-rank onto the 20 removal members of the second semi-rank since, by a centripetal movement of the free ends of the removal members of the second semi-rank, it is safer to have the apexes of the ends of the latter inserted into respective cavities of the removal members of the first semi-rank (see Figs. 71-74). 25 In this context, the term "covering" refers to the partial overlapping of two elements (for example, two removal members, or one removal member and one needle) to allow the passage of a stitch from one to another of said elements without having any dead regions or times in which the stitch 30 is not engaged by one of the two elements. In Fig. 74 at 66, two stitches of the article 6 are schematically represented as they are made to pass from the removal member 26 to the removal member 25, thanks to the above said covering situation. 35 The above described movement is centripetally induced by a

spring (or other elastic body) which is opposed by a semi-ring or semi-crown 24 acting on the inside of stems 250 of the same removal members 25 where a special profile (indicated with 254) acts as a cam upon the variation of 5 longitudinal position of said semi-ring 24. In practice, when the semi-ring 24 interacts with the profile 254 (stem's minor section) the removal member is maintained in the inner position; when, instead, the semi-ring 24 interacts with the removal member's portion closest to apex 251 (major section), 10 the removal member 26 is pushed outwardly. With reference to the examples of the attached drawings, Figs. 75-80 show how the removal member 25 is inclined either inwardly or outwardly according to the operating phase. In particular, Fig. 75 shows (partially) the movable carrier in removal 15 position in which the removal member 25 is kept facing outwardly (direction indicated by the arrow V); on the contrary, in Fig. 76 the removal member is in a stitch-transfer position and is kept facing inwardly by the action of spring 19 (an elastic ring in the illustrated example) 20 being not opposed by the semi-ring 24 which, in fact, lies in the profile 254 of the removal member; again in this figure an arrow (W) indicates the direction of displacement of the removal member 25.

In Figs. 75-83 are shown some details that do not appear in 25 the preceding figures, for example, pneumatic cylinders 29 provided on the arm 10. The pneumatic cylinders 29 operate via relevant rods 90 on a support element 17 exhibiting vertical bars 16 facing downwards. The support element 17 is vertically slidable inside the support body 11, and springs 30 18 are disposed between the latter and the support element 17 to provide a reaction able to push the element 17 upwards, that is, in a direction opposite to that of the downward thrust of rods 90. In some of the drawings, the springs 18 are represented only partially. With reference to Figs. 75-80 35 in particular, the activation of the cylinder 29 causes the

lowering of the rod 90, with the consequent downward displacement of the support element 17. This determines the lowering of the bar 16 which (as indicated by the arrows Z in Fig. 75) pushes down the semi-crown 24, so that the latter, 5 being no longer in correspondence of the cam profile 254, pushes the removal member 25 outwardly (arrow V). On the contrary, when the bar 16 is brought back upwards (arrow T in Fig. 76), the semi-crown 24 too moves up to engage the profile 254, and the action of the spring 19 wins that of the 10 removal member 25 which is thus kept inwardly (arrow W).

Figs. 81-84 show an alternative embodiment of the said removal members 25. In this embodiment, each removal member 25 is fixed on the relevant crown 20, and the covering condition is obtained by disposing the removal members 26 of 15 the first semi-rank and those of the second semi-rank over two ideal circumferences of different radius and/or providing a group (for example, the punches 26) of larger size with respect to the other group of punches. These characteristics are more evident by the detail of Fig. 84 where the punch 26 of the first semi-rank results further externally (as it lies on a circumference of larger radius) than the punch 25 of the second semi-rank and, besides, it has a size larger than the other.

As above mentioned, once the group of plate 5 has been moved 25 away, the movable carrier 300 is placed above the knitting machine 100.

At this point (see Fig. 4), the removal members 25 and 26 are moved closer to the respective needle heads, and the interaction between the needles 2 and removal members 25, 26 30 is similar to that illustrated in Figs. 68-70. Afterwards (Fig. 5), the hook-closing ring 15 is lowered, thereby determining the positioning of the hooks 14 below the stitches to be removed which are, therefore, in their closed configuration. As can be seen in Fig. 6, the support crown 13 35 is lifted, along with the hooks 14 supported by the same

crown, so that the hooks move the article's stitches upwards and the latter disengage from the needles 2 to pass onto the removal members 25 and 26. Thereafter (Figs. 7, 8, 9), the movable carrier 300 is further lifted and moved away from the knitting head 100 to take the article on to a hook-up station provided with an inside-out turning tube 30 in which the article 6 is inserted. The moving of article 6 away from the knitting head 100 can be effected soon after removing the stitches from the needles of the knitting head, as above 5 described, or it can be effected afterwards, for example, in a possible alternative embodiment of the method, after the phase - to be described later on - in which the stitches of the two semi-ranks are moved close to each other.

Figs. 36-53 illustrate embodiments, to be described later on 10 in details, of the inside-out-turning tube 30. The general structure of said tube can be imagined, for example, like a tubular body inside which the article is inserted when the stitches of the last semi-rank, that is, the removed 15 stitches, are still disposed around a circumference, that is, prior to the overturning through 180° of the first semi-rank. Thereafter, by a longitudinal movement, the article engaged 20 on the tube is forced to pass through the open end of the tube, thereby causing the inside-out turning of the article, with the stocking that will be fitted outside the tubular 25 body.

The inside-out-turning tube 30 is then lifted (Figs. 9-11) thus causing the inside-out turning of the article which results fitted on the outside of the tube 30, with the initial end of the same article facing upwards and above the 30 rank of stitches removed by the removal members. In the final phase (illustrated in Fig. 11), the inside-out turning tube 30 is engaged with relevant support means (not shown) in correspondence of its upper end, whereas the lower end of the tube remains free and above the plane of the removed 35 stitches.

The inside-out turning phases above described, and those to be described below for preparing the hook-up operation, can be carried out at any point of the path of the movable carrier, that is, at positions different from the one 5 described herein by way of example.

Afterwards, the hook-closing ring 15 is moved upwards thereby determining the opening of the hooks 14, that is, their displacement in centripetal direction.

At this point (see Figs. 12-14), the stitches of the 10 article's first semi-rank supported by removal members 26 are transferred by an overturning thereof of substantially 180° about the diametral axis which ideally divides the circumference of the removed rank into two semi-ranks. Thus, each removal member 26 of the first semi-rank lies in 15 correspondence of a removal member 25 of the second semi-rank, with the respective free ends close to each other in a configuration similar to that described with reference to Figs. 71-74; in this configuration, each stitch of the first semi-rank results juxtaposed and coaxial to the corresponding 20 stitch of the second semi-rank.

At this point, through the action of a pusher 31 acting from the bottom upwards, a stitch-pushing semi-crown 28 makes the stitches slide along the removal members 26 to take them up onto the removal members 25 of the second semi-ranks located 25 above.

Subsequently, the removal members 26 of the first semi-rank are brought back to their original position by the above said overturning operated in opposite direction.

30 Depicted in the lower side of Fig. 14 is a portion of the hook-up machine 400, comprising a support body 42, a crown 41 with relevant hook-up spines 40, all being well known elements which, therefore, need not to be described in detail.

35 With reference to Figs. 15-18, the hook-up spines 40 are moved close to the removal members 25 which, as already

mentioned, support the two overlapping semi-ranks of the article; afterwards, owing to the downwardly directed push of a stitch-pushing semi-crown 27 coaxial to the circumference formed by the removal members 25, the stitches are

5 transferred onto the spines 40.

The semi-crowns 27 and 28 are shaped alike a semicircular comb, with a series of slots 270 and 280 angularly spaced apart by such extents which correspond to the angular displacement between the removal members 26 and 25, so that

10 the same semi-crowns are able to slide along the removal members while guided vertically by the latter.

15 Shown in Fig. 17 is a hook-up needle 43, by means of which the hook-up of stitches and/or pairs of stitches being fitted on spines is performed in a known manner by carrying out the necessary chain-closing knots.

According to the alternative embodiment illustrated in Figs. 87-88, the pairs of stitches of the two semi-ranks, can be supported - during the closing/hooking-up of the toe of stocking 6 - by the punches 25 of the second semi-rank, and a hook-up needle 43 can be brought close to the latter, which needle, instead of operating the hook-up on spines provided for this purpose, will perform such operation by exploiting the punches 25 which, advantageously, exhibit the said cavity 252, that is, the one used for the engagement of the needle.

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Finally (Fig. 18), once the stitches have been hooked-up onto the spines (or, likewise to the example of Figs. 87-88, onto the punches 25 of the second semi-rank located on the movable carrier), the article 6 is pushed inside the same inside-out turning tube 30 so as to take up a right-side-out condition. This operation can be carried out by using a bar 32 to be inserted into the tube 30 by an extent sufficient to complete the right-side-out arrangement of the article which, after such operation, is definitely ejected.

35 As above mentioned, Figs. 36-53 show exemplary embodiments of

the inside-out-turning tube 30.

One way to perform the introduction of the article into the inside-out-turning tube 30 may consist in aspirating the article inside a single tubular element. With reference to the examples illustrated by the drawings, the body of tube 30 may consist of two coaxial elements 35, 36 whose front or upper ends 350, 360, that is, those facing the article before the inside-out-turning thereof, are so shaped as to define alternately a closed or open ring by a rotation of said two elements relative to each other and about the common longitudinal axis. A so-formed device allows inserting the article thereinside by a transverse movement when the mouth portion is in open condition (semi-ring configuration) and definitely "trapping" the same article by a closing of its perimeter.

The outer tubular element 35 has below a cylindrical closed shape; from its mid portion upwards, it exhibits a semi-cylindrical shape, that is, a wall 353 developing through about 180° on one side only with respect to the longitudinal axis, thereby defining a corresponding lateral opening or port 352 having longitudinal development; in the upper end, the element 35 exhibits a semi-ring 351 defined by a cylindrical surface of a relatively limited height and extending approximately through 180° on the side opposite to the wall 353.

The inner tubular element 36 has in its lower part, likewise the element 35, a closed cylindrical shape; from its mid portion up to the upper end 360, it exhibits a semi-cylindrical shape, that is, a wall 363 developing through approximately 180° on one side only with respect to the longitudinal axis, thereby defining a corresponding lateral opening or port 362 having longitudinal development; the upper end 360 is thus defined by the upper edge 361 of the wall 363.

When the tube 30 is in its open configuration, the semi-ring

351 of the outer element 35 encircles the edge 361 of the inner element; in this way, it is possible to introduce the article 6 inside the tube by a simple translation movement without the need of moving the tube vertically downwards by a 5 stroke which would be substantially equal to the length of the knitted article. This brings about a significant reduction of the apparatus overall dimensions. Thereafter, by a simple relative rotation of the two elements 35 and 36 the tube 30 is closed, thereby allowing the inside-out-turning 10 operation.

The structure of the said tube can be imagined, for example, like a tubular body inside which the article is inserted when the stitches of the last semi-rank, that is, the removed stitches, are still disposed around a circumference, that is, 15 prior to the overturning through 180° of the first semi-rank. Thereafter, by a longitudinal movement, the article engaged on the tube is forced to pass through the open end of the tube and is thus turned inside-out. It will be appreciated that, at this point, the stocking is fitted outside the 20 tubular body. The said tubular body, after the said movement, remains engaged with a support located on the side opposite to the article. After the hook-up operation, the now closed toe of the article will result in proximity of the tube's mouth, so that, by inserting a core of suitable size into the 25 tube's mouth, the same core will be in contact with the article's fabric and, by keeping to move downwards will drive the same article along with it and the latter, by sliding over the edge of the tube will move thereinside by taking up the right-side out configuration which it had originally. 30 Such operation can be carried out and/or assisted by a pneumatic or suction flow. After the ejection of the article, the above described tubular body can be brought back to its initial position to perform its function in the subsequent cycle.

35 Practically, the construction details may vary in any

equivalent way as far as the shape, dimensions, elements disposition, nature of the used materials are concerned, without nevertheless departing from the scope of the adopted solution idea and, thereby, remaining within the limits of
5 the protection granted to the present patent.